## AI for Particle Physics: Better, Smarter, Faster

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#### Outline

#### Particle Physics & AI:

- Particle detectors
- Artificial intelligence

#### Better:

- Recent improvements in AI
- Physics use case: tagging
- Open questions

#### **Smarter:**

- Cutting-edge R&D
- Graph-based algorithms
- Preliminary results

#### **Faster**:

- High Luminosity Upgrade
- Accelerating inference
- Coprocessors as a service



# Particle Physics & AI

#### **Collider Physics**



Largest, highest-energy particle collider
 O Circumference = 27 km (17 mi)

 $\circ$  Center-of-mass energy = 13 TeV

• High data rate requires multiple levels of triggers



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#### **Collider Physics**



- Largest, highest-energy particle collider
  O Circumference = 27 km (17 mi)
  O Center-of-mass energy = 13 TeV
- Focus on AI results from CMS experiment
   Many items also applicable to ATLAS, neutrino physics, cosmology, etc.





- "Hit": energy deposit in single channel
- Tracks: built from consistent hits in tracker, muon chambers
- Clusters: built from nearby hits in calorimeters
- Particles: built from linked tracks and clusters
- Jets: collimated sprays of particles

### Upgrades



- Increase in luminosity → more data!
   Also more radiation...
- Corresponding CMS detector upgrades, including:
  - Pixel (innermost tracker):
    - $66M \rightarrow 1947M$  channels
  - Outer tracker:
    - $9.6M \rightarrow 215M$  channels
  - High Granularity Calorimeter (endcaps):
     85K → 6M channels



#### Neutrino Physics



- Neutrinos interact very rarely and weakly
- Detectors need large volume of material and long exposure
   Try to reduce *backgrounds* (unwanted hits) from cosmic rays, etc.
- Neutrinos have mass and therefore *oscillate* between different flavors
   Near and far detectors compare proportions
- Upcoming LBNF: most intense neutrino beam, 120 GeV

#### What is Artificial Intelligence?

"AI is whatever hasn't been done yet." – Douglas Hofstadter

- In this colloquium: *machine learning* (ML)
- ML is *function approximation*:
  - → map inputs to outputs,  $\vec{x} \mapsto \vec{y}$
  - o  $\vec{y} = F(\vec{x})$  unknown, probably not analytic → try to find approximation  $\vec{y} \approx F'(\vec{x}; \vec{w})$  by optimizing *weights*  $\vec{w}$
- Deep learning:
  - o Use thousands, even millions of weights
  - o Use many layers with intermediate features derived from inputs
    - More "neurons" → more multiplications



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### Training an AI

- Iteratively modify weights so F' gets "closer" to  $\vec{y}$  (training data)
  - o "Closer" defined by a *loss function*

• Use gradient descent to follow change in loss

• Keep separate datasets for testing & validation

o Otherwise, AI could be overtrained





• Training is very intensive: large datasets, billions (!) of multiplications

• GPUs are optimized for these operations

- *Inference*: applying trained AI to (new) input data to get output
  - o Output: classification, regression, etc.

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#### AI at FNAL: A Long History



November 18, 1988 Vol. XI, No. 21

Fermi National Accelerator Laboratory

#### **Neural Network Startup**

In the past few years, there has been a tremendous resurgence in research on neural networks, the name given to arrays of single-bit, quasi-digital processors whose high level of interconnectivity resembles that of nerve cells in the brain. Neural nets seem to be good at problems that humans solve easily, but that conventional computers are notoriously bad at, such as pattern recognition and decision making based on incomplete or faulty data.

Bruce Denby, who has recently joined the Lab as a Wilson Fellow based in the Computing Department, is beginning a project to explore the possibility of using artificial neural networks and other fine-grained SIMD architecture devices in experimental triggers or offline pattern recognition engines.

Networks implemented in VLSI have demonstrated enormous speedups over conventional microprocessors for certain applications. Also, because of the high redundancy in the interconnection network, neural sets are relatively insensitive to localized faults caused by point defects in silicon substrate or by errors in the data input.

Persons wishing to find out more about neural networks should contact Bruce Denby at FNAL::DENBY or drop a note to him at MS 120. If there is sufficient interest, regular discussion sessions can be set up.











#### AI Today



- Massive industry efforts in R&D for deep neural networks
   Many frameworks: TensorFlow, PyTorch, MXNet, scikit-learn, etc.
- Giant leaps in image recognition, language processing, even game playing

   Similar leaps in computational requirements...

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#### **Convolutional Neural Networks**



Image recognition started modern AI revolution

- Innovation: convolutional neural networks (CNNs)
  - o Combine neighboring pixels according to matrix of weights
    - Same convolution applied to whole image  $\rightarrow$  reduce # weights
  - o Derive *features* at different scales: edges, corners, etc.

#### **CNNs** for Neutrinos

#### > Neutrino detector data naturally image-like



current events from cosmic background

<sup>†</sup> <u>JINST 11 (2016 ) P09001</u>, Phys. Rev. Lett. 118 (2017) 231801

### Collider Physics Example: Tagging

Prototypical case: tagging top quarks

- Many models of physics beyond the standard model (SM) include new particles that can decay to top quarks
  - Heavy new particles → boosted top quarks, decay products merge into a single wide jet
- Clear signature of new physics



- o But background events (e.g. SM QCD) have much higher rate
- Traditionally identified using jet substructure:
  - $\circ \vec{x} =$  Nsubjettiness, groomed jet mass, etc. ("expert" variables)
  - $\circ \vec{y} = top quark or QCD$
  - $\circ$  F( $\vec{x}$ ) = selection criteria
    - Example:  $\tau_{32} < 0.6$



### AI for Tagging

- Can machine learning algorithms do a better job than experts?
- Usual progression:
  - Combine expert variables in boosted decision tree (BDT)
  - Combine expert variables in deep neural network (DNN)
  - Use lower-level variables (reconstructed tracks, particles, etc.) in DNN
  - Use more advanced neural network architectures



#### Different Approaches Top quark jet image

ImageTop: build "image" out of jet constituents

- Pros: leverage ubiquitous industry tools for image recognition, convolutional neural networks (CNNs)
- Cons: some information is lost (jets aren't "really" 2D images)



DeepAK8: learn from particle, vertex variables directly

10 15 20 25

**CMS** Simulation

bixel 30

25

20

15

10

5

06

• Pros: keep more information

5

• Cons: 1D convolutions may not fully capture all relationships between quantities

10<sup>-2</sup>

10<sup>-3</sup>

 $10^{-4}$ 

10<sup>-5</sup>

10<sup>-6</sup>

 $10^{-7}$ 

35

pixel<sub>x</sub>

30

#### AI Enables Discovery



Higgs  $\rightarrow \gamma\gamma$ : rare process, but clear signature and clean background

- Boosted decision trees critical for Higgs discovery in 2012
- Event-level classification enhances resonance

Higgs  $\rightarrow$  bb: most common decay, but huge background

- Dedicated DNN tags boosted Higgs with two secondary vertices
- Once thought impossible
  - $\circ$  Now 2.5 $\sigma$  evidence in 2020



### **Open Questions**

- How to handle differences between data and simulation?
  - o Gradient reversal (domain adaptation) very promising
    - Can also help avoid other unwanted behavior, e.g. mass dependence
- How to explain what the network learns?
  - o Should probably be an entire academic field in itself
  - o See e.g. The Building Blocks of Interpretability for CNNs
- Far from an exhaustive list (of algorithms or questions)





#### Cutting Edge Tagging

Tagger	AUC	Acc	$1/\epsilon_{B}^{*}$	# Params
P-CNN	0.980	0.930	759	348K
ResNet50 <sup>†</sup>	0.983	0.935	1000	25M
ResNeXt	0.984	0.936	1147	1.46M
ParticleNet	0.986	0.940	1615	366K
† <u>CSBS 3 (2019) 13</u>		* ( $\epsilon_{\rm S} = 0.3$ )		).3)

- P-CNN = simplified DeepAK8
- Apply massive image recognition networks (from industry) for significant gains
  - o But regular grids unnatural for collider data
    - sparse occupancy, varying geometry, etc.
- ParticleNet does even better with far fewer parameters...
  - $\circ$  But more operations: 3–4× ResNeXt



#### All Roads Lead to Graphs

- Generalize convolutions → message passing w/ graphs (nodes & edges)
   O Derive new features for node x<sub>i</sub> using neighbors x<sub>j</sub>
  - o Can even assign features to edges



- Aside: recurrent networks (RNNs) for language processing now supplanted by "Transformers" that use "attention"
  - o These are just graphs!



#### Graph Networks (GNNs) for Physics

• ParticleNet (leading top tagger) uses "point cloud" (also a GNN)

o Also called "interaction networks", "graph CNNs", etc.

o Same techniques applicable to many other tasks...



- Most fundamental problems in event reconstruction: *tracking*, *vertexing*, *clustering*
- $\succ$  How to associate detector hits with other detector hits
  - Detector geometry very important!

#### **GNNs** for Tracking

**GNN** 





- First application to reconstruction: tracking
- Start w/ possible connections between hits
- *Edge classification*: GNN decides which edges are correct
- Work in progress: 97% efficient



#### GNNs for Clustering

- CMS upgrades (~2026) include integrated endcap High Granularity Calorimeter
  - o Hexagonal wafers increase silicon yield
  - Especially non-grid-like geometry





- Edge classification works well for clustering
- Charged pion: >90% efficiency to find correct edges (99% for photons and muons)
  - 98–99% correct energy assignment

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#### Edge Determination

- Default edge assignment: use k-nearest neighbors or similar algorithm (based on detector geometry)
- GravNet: edges determined dynamically

   k-nearest neighbors using *derived features* GNN optimizes latent space to associate detector hits
- Open question: how to handle unknown number of clusters?





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#### Graphs for Calibration

- *Calibration*: another fundamental problem in physics
   o Raw measurements usually have some bias
- Dynamic reduction network: <u>arXiv:2003.08013</u>



- Preliminary results (hadron resolution)
  - competitive w/ expert algorithms
  - o Approach still being refined
  - Also studying industry benchmarks such as MNIST





### Computing for AI

- AI has significant impacts on physics:
  - o Helps us do things we couldn't do before
    - e.g. tag top and bottom quarks with unprecedented accuracy
  - o Helps us do better at fundamental problems
    - Tracking, clustering, calibration, etc.
- But can we afford to keep doing all of this?
  HL-LHC is just around the corner...





HGCal simulation, 200 simultaneous pp collisions

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#### More Data, More Problems





- HL-LHC vital statistics:
  - o 10× data vs. Run 2/3
  - 200 simultaneous collisions
     vs. ~30 in Run 2
  - Detector upgrades: 15–65× increase in channels
- More data and more complexity
  - DUNE, LSST, SKA will provide similarly huge datasets
- Data volumes will approach scale of Google and Facebook
  - o But computing resources won't...

#### **CPU Stagnation**

WLCG provides:

- 42 countries
- 170 computing centers
- > 2 million tasks/day
- 1 million CPU cores
- 1 exabyte of storage

42 Years of Microprocessor Trend Data





Original data up to the year 2010 collected and plotted by M. Horowitz, F. Labonte, O. Shacham, K. Olukotun, L. Hammond, and C. Batten New plot and data collected for 2010-2017 by K. Rupp

- Moore's Law continues
  O But without Dennard scaling
- Single-thread performance can't keep up with accelerator intensity
- Projected shortfalls 2–10×, depending on assumptions

#### Heterogeneous Revolution



- New coprocessors provide efficiency at expense of flexibility
  - o GPU: execute serial instructions on massive data
  - o FPGA: spatial computing (execute many instructions simultaneously)
- Luckily, optimized for machine learning!







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#### AI & Coprocessors: Two Great Tastes...

- Just adding new tagging algorithms doesn't speed up reconstruction
   o ResNet50 inference on CPU: ~1 sec/image
- Focus on *replacing* classical algorithms with AI
  - Fundamental problems (clustering, etc.) involve comparing all detector hits to all other detector hits
  - O(N<sup>2</sup>) operation, can be reduced to O(NlogN) w/ clever techniques • AI inference is O(N) → *much* better scaling w/ detector occupancy
- Use coprocessors to accelerate AI inference
  - GPUs also useful for training, but training only uses subset of data
  - Inference must be performed for every event (*billions*, at least)



### AI for Triggers

- CMS L1 trigger uses FPGAs to satisfy extreme latency requirements (~1  $\mu$ s)
- **hls4ml**: open-source package
  - o Optimize ML algorithms to run efficiently on FPGAs
  - o Handles BDTs, various DNN architectures
- Planned for use during LHC Run 3





- Offline computing: looser latency requirements
- Multiple CPUs send inference requests to coprocessor server
- Ensures optimal utilization of GPUs/FPGAs, along with flexibility
- One coprocessor could serve ~100 CPUs
  - Depending on conditions and requirements: latency, bandwidth, memory, inference time, etc.
  - $\circ$  Much more cost effective than buying 1 GPU for every CPU in the grid...

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### LHC Computing Model

- Inference as a service naturally fits into existing computing model
- Reconstruction process involves 100s of algorithms
  - o Only a few worth accelerating



- Current• Most efficient method:<br/>asynchronous, non-<br/>blocking calls
  - Enabled by task-based multithreading
  - CPU can do other work while inference request is ongoing
    - Significantly reduces impact of network latency

### SONIC Approach

- SONIC (Services for Optimized Network Inference on Coprocessors): inference as a service in experiment software frameworks
- ✓ Use industry tools:
  - o gRPC communication
  - o TensorFlow or Nvidia Triton inference servers
  - o Kubernetes for dynamic scaling of resources
    - Interact with cloud services: Azure, AWS, GCP
- ✓ Avoid rewriting millions of lines of C++ algorithm code in specialized coprocessor languages
  - User code just converts input and output data into desired formats





#### **Heterogeneous Edge Resource**



- Cloud service has higher latency
- Local installation of coprocessors: "on-prem" or "edge"
- Provides test of ultimate performance
- Use gRPC protocol either way

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- Microsoft Brainwave FPGA, ResNet50 top tagger inference
- Latency: time for single request to complete

 $\circ$  (CPU) = 500–1000 ms, (remote) = 60 ms, (on-prem) = 10 ms

- Throughput: requests per second
  - o FPGA processes one image at a time, very quickly (1.8 ms)
  - o GPU (GTX 1080) needs batch of ~50 images to attain similar throughput

#### Scaling Up GPUs



• Use Kubernetes + Triton to deploy multi-GPU server

o More GPUs support more CPUs, higher throughput

- Triton supports dynamic batching: combine requests from multiple CPUs
  - $\circ$  Huge increase in throughput for large networks with small batch size



DUNE: Deep Underground Neutrino Experiment

- Largest liquid argon detector ever designed
- ~1M channels, 1 ms integration time w/ MHz sampling → 30+ petabytes/year
   Rate ultimately limited by available computing
- ProtoDUNE operating at CERN (5% size of DUNE)

#### v-SONIC



#### all CPU

- ProtoDUNE reconstruction dominated by single ML algorithm
- Offload to GPU as a service: >2× overall improvement!
  - Simple implementation
     w/ blocking, synchronous call
  - o Latency preferable to CPU inference

Process	Time [s] (all CPU)	Time [s] (w/ GPU)
Full event	227	99
ML algorithm (EmTrackMichelId)	142	10

w/ GPU

#### Conclusions

- Major strides in deep learning have been incorporated in particle physics
- Significant improvements in top quark tagging (and other tasks)
- AI enables new avenues for discovery, such as boosted  $H \rightarrow b\bar{b}$
- Many open questions remain
- Moving beyond fully-connected and convolutional neural networks
   → generalize by embedding data in graphs
- Cutting-edge techniques can handle fundamental tasks: tracking, clustering, calibration
- Faster

Better

Smarter

- Need to accomplish fundamentals and encourage new capabilities, while coping with unprecedented floods of data
- Solution: accelerate AI inference with coprocessors as a service
- Promising and achievable path for colliders, neutrinos, & beyond!

### Backup

#### Jet Substructure



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#### AI for b-tagging

- Similar progression to top tagging:
   o Expert variables
  - Expert variables combined in **BDT**
  - Expert variables combined in DNN
  - o Low-level variables improve DNN
- Double-b-tagging benefits similarly
  - o "Expert" corresponds to b-tagging subjets







### **Tagging New Particles**

- Many new AI approaches being developed all the time
   Access to tools, frameworks, computing constantly increasing
- Can even tag new particles (beyond the SM)
   e.g. displaced jets from long-lived particles
- Gradient reversal employed to avoid data/simulation discrepancies

